

(1) The Hénon dynamical system in \mathbb{R}^2 is defined by

$$\left. \begin{aligned} x_{n+1} &= a - by_n - x_n^2, \\ y_{n+1} &= x_n \end{aligned} \right\} \quad (DS),$$

where $a, b \in \mathbb{R}$ are parameters.

- (a) For which range of values of the parameters a and b does (DS) have two fixed points? /5
- (b) Determine the stability of the linearized system at each fixed point when $a = 3, b = -1$. /5
- (c) When $a = -3/4$ and $b = 1$, the point $(-\frac{1}{2}, -\frac{1}{2})$ is a fixed point. Does the linearized system determine the stability of this fixed point? /5
- (d) Continuing with $a = -3/4, b = 1$, introduce the coordinates $u = x + \frac{1}{2}, v = y + \frac{1}{2}$. (DS) is transformed to

$$\left. \begin{aligned} u_{n+1} &= u_n - v_n - u_n^2, \\ v_{n+1} &= u_n \end{aligned} \right\} \quad (DS')$$

Introduce the complex variable $z = cu + v$ and transform (DS') into the system

$$z_{n+1} = \lambda z_n + \alpha z_n^2 + \beta z_n \bar{z}_n + \gamma \bar{z}_n^2 \quad (CDS)$$

Determine the constants $c, \lambda, \alpha, \beta$ and γ . /8

- (e) Determine the stability of the fixed point $z = 0$ for (CDS). Explain your reasoning. /2

A helpful formula: $h = \operatorname{Re} \left[\frac{m}{\lambda} + \frac{(2\lambda-1)\alpha\beta}{\lambda^2(\lambda-1)} \right] - \frac{1}{2}|\beta|^2 - |\gamma|^2$.

- (2) Let $G(x) = 6x(1 - x)$ for $x \in [0, 1]$.
- (a) Find the subintervals $I_0 = [0, a]$ and $I_1 = [b, 1]$ of $I = [0, 1]$ such that $G^{-1}(I) = I_0 \cup I_1$. /2
- (b) G has two fixed points in I . Indicate their stability. /3
- (c) Let $\Lambda = \{x \in I : \forall k \geq 0, G^k(x) \in I\}$. Describe Λ in terms of the sets I_0 and I_1 . /1
- (d) Let $\Sigma = \{\omega = (\omega_0, \omega_1, \dots) : \forall i \geq 0, \omega_i \in \{0, 1\}\}$. Define a metric d on Σ . Prove that the set $U = \{\omega \in \Sigma : \omega_0 = 1, \omega_1 = 0\}$ open in the topology of (Σ, d) . /4
- (e) Define the 1-sided shift map on two symbols, $\sigma : \Sigma \rightarrow \Sigma$. /2
- (f) Define an itinerary map, h , for $G|_\Lambda$. /1
- (g) Show that the itinerary map is continuous, 1-1 and onto. [Indicate which, if any, theorems you use in the proof.] /7
- (h) How many period-2 points does G have? How many prime period-8 points? /5

[Please turn over]

(3) Define a dynamical system on \mathbb{R}^2 by

$$\begin{aligned}x_{n+1} &= 2x_n + 3y_n - (x_n - y_n)^2 \\y_{n+1} &= \frac{1}{2}y_n + \frac{1}{2}(x_n - y_n)^2.\end{aligned}\tag{DS}$$

(a) Show that the origin is a hyperbolic fixed point of (DS). /2

(b) Let $\mathbf{v}_+ = \begin{pmatrix} * \\ 1 \end{pmatrix}$ (resp. $\mathbf{v}_- = \begin{pmatrix} 1 \\ * \end{pmatrix}$) span the stable (resp. unstable) subspace of $(0, 0)$. Find \mathbf{v}_+ and \mathbf{v}_- . /3

(c) Introduce a system of coordinates (u^+, u^-) adapted to the stable and unstable subspaces. Express (DS) in the form

$$\begin{aligned}u_{n+1}^+ &= au_n^+ + p_0(u_n^+)^2 + p_1u_n^+u_n^- + p_2(u_n^-)^2 \\u_{n+1}^- &= bu_n^- + q_0(u_n^+)^2 + q_1u_n^+u_n^- + q_2(u_n^-)^2\end{aligned}\tag{ADS}.$$

Determine the coefficients a, b, p_i, q_j for $i, j = 0, 1, 2$. /5

(d) Find the Maclaurin series for W_{loc}^+ and W_{loc}^- , up to second order, in the coordinates (u^+, u^-) . /10

(e) Sketch the stable and unstable subspaces and manifolds in the (u^+, u^-) coordinates. Indicate how orbits beginning on the manifolds behave, and how nearby orbits behave. /5

[Please turn over]

(4) (a) State Sharkovskii's theorem. /5

(b) Let $f : [0, 1] \rightarrow [0, 1]$ be a continuous, surjective function whose graph is shown in figure 1. Prove: for each positive integer n , f has a periodic orbit of prime period n . /8

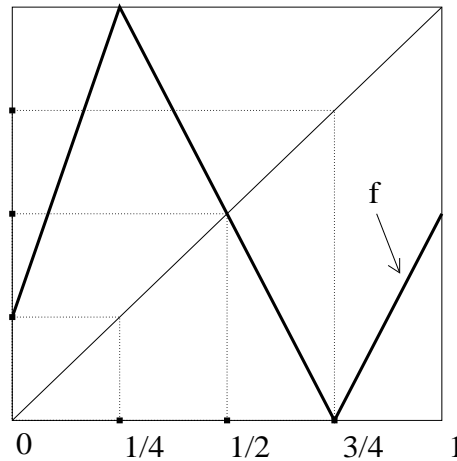


FIGURE 1. $f : [0, 1] \rightarrow [0, 1]$.

(c) Let $x_{n+1} = f_\mu(x_n)$ where $f_\mu(x) = x + \mu + x^2$ for $x, \mu \in \mathbb{R}$.

(i) Find the fixed points of this dynamical system. /2

(ii) Find the value of μ for which there is a saddle-node bifurcation. /1

(iii) Find the value of μ for which there is a flip bifurcation. Is it super- or sub-critical? /6

(iv) Sketch the bifurcation diagram in the (μ, x) plane. /3

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