

(1) The Hénon dynamical system in \mathbb{R}^2 is defined by

$$\left. \begin{aligned} x_{n+1} &= a - by_n - x_n^2, \\ y_{n+1} &= x_n \end{aligned} \right\} \quad (DS),$$

where $a, b \in \mathbb{R}$ are parameters.

(a) For which range of values of the parameters a and b does (DS) have two fixed points? /5

(b) Determine the stability of the linearized system at each fixed point when $a = 3, b = -1$. /5

(c) When $a = -3/4$ and $b = 1$, the point $(-\frac{1}{2}, -\frac{1}{2})$ is a fixed point. Does the linearized system determine the stability of this fixed point? /5

(d) Continuing with $a = -3/4, b = 1$, introduce the coordinates $u = x + \frac{1}{2}, v = y + \frac{1}{2}$. (DS) is transformed to

$$\left. \begin{aligned} u_{n+1} &= u_n - v_n - u_n^2, \\ v_{n+1} &= u_n \end{aligned} \right\} \quad (DS')$$

Introduce the complex variable $z = cu + v$ and transform (DS') into the system

$$z_{n+1} = \lambda z_n + \alpha z_n^2 + \beta z_n \bar{z}_n + \gamma \bar{z}_n^2 \quad (CDS)$$

Determine the constants $c, \lambda, \alpha, \beta$ and γ . /8

(e) Determine the stability of the fixed point $z = 0$ for (CDS). Explain your reasoning. /2

$$\text{A helpful formula: } h = \operatorname{Re} \left[\frac{m}{\lambda} + \frac{(2\lambda-1)\alpha\beta}{\lambda^2(\lambda-1)} \right] - \frac{1}{2}|\beta|^2 - |\gamma|^2.$$

Solution.

(a) (DS) has a fixed point at (x, y) iff $x = a - by - x^2$ and $y = x$ [2 marks] iff $y = x$ and $x^2 + (1+b)x - a =$

0 [1 mark]. There are two distinct f.p.s iff the discriminant $\Delta^2 = (1+b)^2 + 4a$ is positive [1 mark]. Therefore,

$$a > -\frac{1}{4}(1+b)^2, \quad b \in \mathbb{R}. \quad [1 \text{ mark}]$$

- (b) When $a = 3, b = -1$, the fixed points are $x = y = \pm\sqrt{3}$ [1 mark]. The linearized map is

$$df_{(x,y)} = \begin{bmatrix} -2x & -b \\ 1 & 0 \end{bmatrix}. \quad [1 \text{ mark}]$$

We get

$$df_{(\pm\sqrt{3}, \pm\sqrt{3})} = \begin{bmatrix} \mp 2\sqrt{3} & 1 \\ 1 & 0 \end{bmatrix}. \quad [1 \text{ mark}]$$

The eigenvalues are $\mp(\sqrt{3} \pm 2)$ [1 mark]. Thus, the fixed points are saddles, hence unstable [1 mark].

- (c) The linearized map at $(-\frac{1}{2}, -\frac{1}{2})$ is

$$\begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} \quad [1 \text{ mark}]$$

which has characteristic polynomial $\lambda^2 - \lambda + 1$ [1 mark]. The roots are cube roots of -1 -- hence of unit modulus [1 mark]. Therefore, the linearized system does not determine the stability of the nonlinear system [2 marks].

- (d) Let g denote the map defined by (DS'). Then $dg_{(0,0)}$ is the matrix in the previous equation [1 mark]. Let $\lambda, \bar{\lambda}$ be its eigenvalues with $\lambda = \frac{1}{2} + i\frac{\sqrt{3}}{2}$. The λ -th eigenvector of $A = dg_{(0,0)}^T$ is

$$\begin{bmatrix} -\lambda \\ 1 \end{bmatrix}. \quad [1 \text{ mark}]$$

This gives $c = -\lambda$ [1 mark]. It follows that $z = (v - \frac{1}{2}u) - i\frac{\sqrt{3}}{2}u$ [1 mark]. Thus $u = \frac{i}{\sqrt{3}}(z - \bar{z}) = bz + \bar{b}\bar{z}$ and $v = \frac{1}{2}u + \frac{1}{2}(z + \bar{z}) = az + \bar{a}\bar{z}$ where $a = \frac{1}{2} + \frac{i}{2\sqrt{3}}$ and $b = \frac{i}{\sqrt{3}}$ [1 mark]. Then

$$\begin{aligned} z_{n+1} &= -\lambda u_{n+1} + v_{n+1}, & [1 \text{ mark}] \\ &= -\lambda(u_n - v_n - u_n^2) + u_n, \\ &= (1 - \lambda)u_n + \lambda v_n + \lambda u_n^2, \\ &= \lambda(-\lambda)u_n + \lambda v_n + \lambda(b^2 z_n^2 + |b|^2 z\bar{z} + \bar{b}^2 \bar{z}^2), \\ &= \lambda z_n + \lambda b^2 z_n^2 + 2\lambda |b|^2 z\bar{z} + \lambda \bar{b}^2 \bar{z}^2, & [1 \text{ mark}] \end{aligned}$$

where we have used that $-\lambda^2 = 1 - \lambda$. This proves that

$$\begin{aligned}\lambda &= \frac{1}{2} + i\frac{\sqrt{3}}{2}, & \alpha &= \lambda b^2 = -\lambda/3, \\ \beta &= 2\lambda|b|^2 = 2\lambda/3, & \gamma &= \lambda\bar{b}^2 = -\lambda/3.\end{aligned}\quad [1 \text{ mark}]$$

- (e) We know that there is a coordinate transformation $w = f(z)$ such that our dynamical system becomes $w_{n+1} = \lambda w_n + q w_n^2 \bar{w}_n + O(|w_n|^4)$ and $|w_{n+1}|^2 = |w_n|^2 + 2h|w_n|^4 + O(|w_n|^5)$, where h is the real part of q/λ [1 mark]. The sign of h therefore determines the stability of 0. From the helpful formula, we know that

$$h = \operatorname{Re} \left[\frac{m}{\lambda} + \frac{(2\lambda - 1)\alpha\beta}{\lambda^2(\lambda - 1)} \right] - \frac{1}{2}|\beta|^2 - |\gamma|^2,$$

where $m = 0$ is the coefficient on $z_n^2 \bar{z}_n$. We compute that

$$\begin{aligned}\frac{(2\lambda - 1)\alpha\beta}{\lambda^2(\lambda - 1)} &= \frac{i\sqrt{3} \times (-\lambda/3) \times (2\lambda/3)}{-\lambda} \\ &= \frac{i}{3\sqrt{3}} \times (1 + i\sqrt{3}) \\ &= \frac{-1}{3} + i\frac{1}{6\sqrt{3}}.\end{aligned}$$

Therefore

$$h = -\frac{1}{3} - \frac{1}{2}|\beta|^2 - |\gamma|^2 < 0.$$

Therefore, the origin is stable [1 mark].

- (2) Let $G(x) = 6x(1 - x)$ for $x \in [0, 1]$.
- (a) Find the subintervals $I_0 = [0, a]$ and $I_1 = [b, 1]$ of $I = [0, 1]$ such that $G^{-1}(I) = I_0 \cup I_1$. /2
- (b) G has two fixed points in I . Indicate their stability. /3
- (c) Let $\Lambda = \{x \in I : \forall k \geq 0, G^k(x) \in I\}$. Describe Λ in terms of the sets I_0 and I_1 . /1
- (d) Let $\Sigma = \{\omega = (\omega_0, \omega_1, \dots) : \forall i \geq 0, \omega_i \in \{0, 1\}\}$. Define a metric d on Σ . Prove that the set $U = \{\omega \in \Sigma : \omega_0 = 1, \omega_1 = 0\}$ open in the topology of (Σ, d) . /4
- (e) Define the 1-sided shift map on two symbols, $\sigma : \Sigma \rightarrow \Sigma$. /2
- (f) Define an itinerary map, h , for $G|_\Lambda$. /1
- (g) Show that the itinerary map is continuous, 1-1 and onto. [Indicate which, if any, theorems you use in the proof.] /7
- (h) How many period-2 points does G have? How many prime period-8 points? /5

Solution.

- (a) We want to find solutions to $G(x) = 1$ [**1 mark**].
Thus $6x^2 - 6x + 1 = 0$ or $a = \frac{6 - \sqrt{12}}{12} = \frac{1}{2} - \frac{1}{\sqrt{12}}$, $b = \frac{6 + \sqrt{12}}{12} = \frac{1}{2} + \frac{1}{\sqrt{12}}$ [**1 mark**].
- (b) We know that the fixed points of G lie in $I_0 \cup I_1$ since they stay in I under an iteration [**1 mark**].
We know that $G'(x) = 6 - 12x$ so $G'(x) \geq 6 - 12a = \sqrt{12}$ on I_0 [**1 mark**]. By symmetry, $|G'(x)| \geq \sqrt{12}$ on $I_0 \cup I_1$. Therefore, the fixed points are repellers [**1 mark**].
- (c) Λ is the set of points in $I_0 \cup I_1$ whose positive orbit lies in $I_0 \cup I_1$ [**1 mark**].

(d) We define a metric d on Σ by

$$d(\omega, \eta) = \sum_{k=0}^{\infty} \frac{|\omega_k - \eta_k|}{2^k}, \quad [1 \text{ mark}]$$

for all $\omega, \eta \in \Sigma$. To prove that U is open in (Σ, d) , it suffices to prove that for all $\omega \in U$, there is a ball of radius r about ω contained in U [1 mark]. Now, if $d(\omega, \eta) < 1/2$, then we must have that $\omega_k = \eta_k$ for $k = 0, 1$ [1 mark]. This proves that the ball of radius $1/2$ about ω is contained in U for any $\omega \in U$. Thus U is open [1 mark].

(e) For each $\omega \in \Sigma$: $\sigma(\omega)_k = \omega_{k+1}$ for all $k \geq 0$ [2 marks].

(f) Given $x \in \Lambda$, define the itinerary map $h(x)$ to equal $\omega \in \Sigma$ iff $G^k(x) \in I_{\omega_k}$ for all $k \geq 0$ [1 mark]. Since $I_0 \cap I_1 = \emptyset$, this is well-defined.

(g) Proof that h is continuous, 1-1 and onto. For each $n \geq 0$ and $\omega \in \Sigma$, define

$$I_{\omega_0, \dots, \omega_n} = \{x \in I : G^k(x) \in I_{\omega_k} \ \forall k = 0 \dots n\}. \quad [1 \text{ mark}]$$

Let $\mu = \sqrt{12}$, which is a lower bound for $|G'|$ on $I_0 \cup I_1$.

CLAIM. $I_{\omega_0, \dots, \omega_n}$ is an interval in I_{ω_0} of length $\leq \mu^{-n}$ for all ω, n [1 mark].

CHECK. If $n = 0$, then the claim follows since $I_{0,1}$ is an interval of length at most $1 = \mu^{-0}$. Therefore, assume the claim is true for $\leq n-1$ and all ω . The set $I_{\omega_1, \dots, \omega_n}$ is therefore an interval in I_{ω_1} of length $\leq \mu^{-n+1}$. The set $I_{\omega_0, \dots, \omega_n}$ is therefore the intersection of $G^{-1}(I_{\omega_1, \dots, \omega_n})$ with I_{ω_0} . Since $G|_{I_{\omega_0}}$ is a homeomorphism, we have proven that $I_{\omega_0, \dots, \omega_n}$ is an interval. To prove the claim about the length, if $x, y \in I_{\omega_0, \dots, \omega_n}$, then $|G(x) - G(y)| \leq \mu^{-n+1}$. On the other hand, the MVT plus the lower bound for $|G'|$ gives $|G(x) - G(y)| \geq \mu|x-y|$. Putting the two inequalities together shows that $|x-y| \leq \mu^{-n}$, which proves the claim [2 marks].

CLAIM. h is onto and 1-1.

CHECK. For each $\omega \in \Sigma$, the sets are nested: $I_{\omega_0} \supset I_{\omega_0, \omega_1} \supset \dots \supset I_{\omega_0, \dots, \omega_n} \supset \dots$. Since each is compact, their intersection is non-empty. This proves that h is onto. Since the diameter goes to zero, there is a unique point x in their intersection. This proves h is 1-1 [1 mark].

CLAIM. h is continuous.

CHECK. Let $x \in \Lambda$ and let $\omega = h(x)$. Let $\epsilon > 0$ be

given. Choose $N > \log_2 \epsilon^{-1}$ and let $\delta = 6^{-N}$. Let $x' \in \Lambda$ be s.t. $|x - x'| < \delta$. Let $\omega' = h(x')$. The MVT implies that for $k < N$

$$|G^k(x) - G^k(x')| \leq 6^k |x - x'| \leq 6^{k-N} \leq 6^{-1} < b - a,$$

since $|G'| \leq 6$ on I . This implies that

$$x, x' \in \Lambda, |x - x'| < \delta \implies d(h(x), h(x')) \leq \epsilon.$$

Indeed, if $d(\omega', \omega) > \epsilon$, then there is a smallest $k < \log_2 \epsilon^{-1} < N$ s.t. $\omega'_k \neq \omega_k$. Thus, the k -th iterate of x and x' lie in opposite intervals and so they are separated by at least $b - a$. This does not happen by the above calculation. This proves the continuity of h [2 marks].

- (h) Since any periodic point of G must lie in Λ , and h is a bijection, it suffices to count periodic points of the shift map [2 marks]. Let P_n (resp. p_n) be the number of period- n (resp. prime period- n) points for the shift map. We know that

$$P_n = \#\{\text{binary numbers with } n \text{ digits.}\} = 2^n. \quad [1 \text{ mark}]$$

Thus

$$P_2 = 4.$$

On the other hand, a period- n point that is not a prime period- n point must also be a periodic point of period $k < n$, k a divisor of n [1 mark]. For $n = 2^3$, this implies that any non-prime period-8 point is of period 4, so

$$p_8 = P_8 - P_4 = 2^8 - 2^4 = 240. \quad [1 \text{ mark}]$$

(3) Define a dynamical system on \mathbb{R}^2 by

$$\begin{aligned} x_{n+1} &= 2x_n + 3y_n - (x_n - y_n)^2 \\ y_{n+1} &= \frac{1}{2}y_n + \frac{1}{2}(x_n - y_n)^2. \end{aligned} \quad (DS)$$

(a) Show that the origin is a hyperbolic fixed point of (DS).

/2

(b) Let $\mathbf{v}_+ = \begin{pmatrix} * \\ 1 \end{pmatrix}$ (resp. $\mathbf{v}_- = \begin{pmatrix} 1 \\ * \end{pmatrix}$) span the stable (resp. unstable) subspace of $(0, 0)$. Find \mathbf{v}_+ and \mathbf{v}_- .

/3

(c) Introduce a system of coordinates (u^+, u^-) adapted to the stable and unstable subspaces. Express (DS) in the form

$$\begin{aligned} u_{n+1}^+ &= au_n^+ + p_0(u_n^+)^2 + p_1u_n^+u_n^- + p_2(u_n^-)^2 \\ u_{n+1}^- &= bu_n^- + q_0(u_n^+)^2 + q_1u_n^+u_n^- + q_2(u_n^-)^2 \end{aligned} \quad (ADS).$$

Determine the coefficients a, b, p_i, q_j for $i, j = 0, 1, 2$.

/5

(d) Find the Maclaurin series for W_{loc}^+ and W_{loc}^- , up to second order, in the coordinates (u^+, u^-) .

/10

(e) Sketch the stable and unstable subspaces and manifolds in the (u^+, u^-) coordinates. Indicate how orbits beginning on the manifolds behave, and how nearby orbits behave.

/5

Solution.

(a) The linearization at $(0, 0)$ has the matrix

$$\begin{bmatrix} 2 & 3 \\ 0 & 1/2 \end{bmatrix} \quad [1 \text{ mark}]$$

which has eigenvalue $2, 1/2$ [1 mark].

(b) The unstable eigenvector is $\mathbf{v}_- = [1, 0]^T$ [1 mark].
The stable eigenvector solves $\frac{3}{2}x + 3y = 0$ [1 mark],
so we can choose $\mathbf{v}_+ = [-2, 1]^T$ [1 mark].

(c) We have that $x = u^- - 2u^+$ and $y = u^+$ [1 mark].
Thus $u^+ = y$ and $u^- = x + 2y$ and $x - y = u^- - 3u^+$ [1

mark]. (DS) is transformed into

$$\begin{bmatrix} u_{n+1}^+ \\ u_{n+1}^- \end{bmatrix} = \begin{bmatrix} \frac{1}{2}y_n + (x_n - y_n)^2 \\ 2x_n + 3y_n - (x_n - y_n)^2 + 2(\frac{1}{2}y_n + \frac{1}{2}(x_n - y_n)^2) \end{bmatrix} \quad [1 \text{ mark}]$$

$$= \begin{bmatrix} \frac{1}{2}u_n^+ + (3u_n^+ - u_n^-)^2 \\ 2u_n^- \end{bmatrix} \quad [1 \text{ mark}]$$

(d) By inspection $u^- = 0$ is invariant, hence $W_{loc}^+ = \{(u^+, 0)\}$ [1 mark]. On the other hand, assume that $u^+ = g(u^-) = a_2(u^-)^2 + \dots$ is the local unstable manifold expressed as the graph of a function up to second order [1 mark]. Then

$$\begin{aligned} u_{n+1}^+ &= \frac{1}{2}u_n^+ + (3u_n^+ - u_n^-)^2 && \text{using part (c)} \\ &= \frac{1}{2}g(u_n^-) + (3g(u_n^-) - u_n^-)^2 && \text{using } u^+ = g(u^-) \\ &= \left(\frac{1}{2}a_2 + 1\right)(u_n^-)^2 + \dots && \text{expanding } g(u^-) [1 \text{ mark}] \end{aligned}$$

while,

$$\begin{aligned} u_{n+1}^+ &= g(u_{n+1}^-) && \text{using invariance of } W_{loc}^+ \\ &= g(2u_n^-) && \text{using part (c)} \\ &= 4a_2(u_n^-)^2 + \dots && \text{using } g(u^-) = a_2(u^-)^2 + \dots [2 \text{ marks}] \end{aligned}$$

We equate coefficients and deduce

$$a_2 = \frac{2}{7} \quad [1 \text{ mark}].$$

Thus,

$$W_{loc}^- = \{(2(u^-)^2/7, u^-)\} \quad [2 \text{ marks}].$$

(e) Mark scheme for sketch:

- (i) Correct labels [2 marks].
- (ii) Correct orientation of manifolds [1 mark].
- (iii) Correct arrows [1 mark].

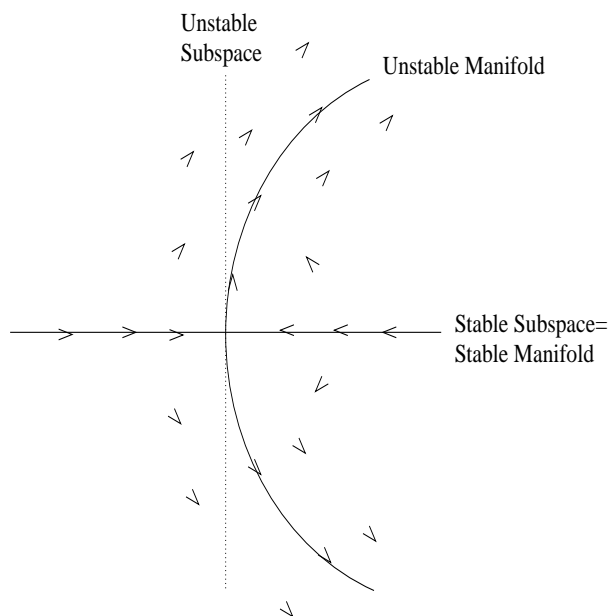


FIGURE 1. The stable and unstable manifolds of (DS).

(4) (a) State Sharkovskii's theorem. /5

(b) Let $f : [0, 1] \rightarrow [0, 1]$ be a continuous, surjective function whose graph is shown in figure 2. Prove: for each positive integer n , f has a periodic orbit of prime period n . /8

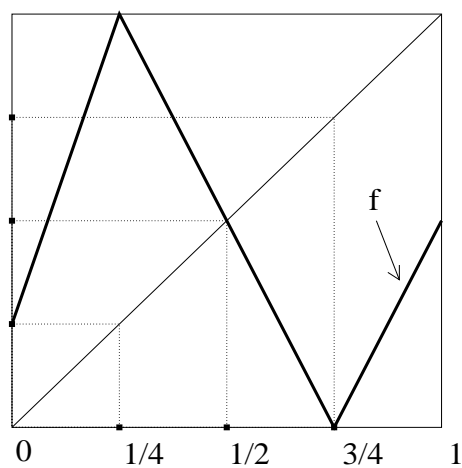


FIGURE 2. $f : [0, 1] \rightarrow [0, 1]$.

(c) Let $x_{n+1} = f_\mu(x_n)$ where $f_\mu(x) = x + \mu + x^2$ for $x, \mu \in \mathbb{R}$.

- (i) Find the fixed points of this dynamical system. /2
- (ii) Find the value of μ for which there is a saddle-node bifurcation. /1
- (iii) Find the value of μ for which there is a flip bifurcation. Is it super- or sub-critical? /6
- (iv) Sketch the bifurcation diagram in the (μ, x) plane. /3

Solution.

- (a) Define the an ordering \triangleleft on the positive integers by [1 mark]

$$3 \triangleleft 5 \triangleleft 7 \triangleleft \dots \triangleleft 2 \cdot 3 \triangleleft 2 \cdot 5 \triangleleft 2 \cdot 7 \triangleleft \dots \triangleleft 2^n \cdot 3 \triangleleft 2^n \cdot 5 \triangleleft 2^n \cdot 7 \triangleleft \dots \dots \triangleleft 2^n \triangleleft \dots \triangleleft 2^2 \triangleleft 2^1 \triangleleft 2^0,$$

[2 marks] where we enumerate all odd primes in increasing order, then twice the odd primes, and so on, and finally all powers of 2.

Recall that a point x has prime period n if it is a fixed point of f^n and not of f^k for any $k < n$ [1 mark].

Sharkovskii's Theorem. Let $f : [0, 1] \rightarrow [0, 1]$ be a continuous map. If f has a periodic point of prime period n , then f has a periodic point of prime period k for all $n \triangleleft k$ [1 mark].

- (b) By Sharkovskii's theorem, it suffices to prove that f has a periodic point of prime period 3 [1 mark]. Let $I_0 = [0, 1/4]$, $I_1 = [1/4, 3/4]$ and $I_2 = [3/4, 1]$ [1 mark]. By inspection of the graph of f it is clear that f is continuous and
- (i) $f(I_0) \supset I_1$;
 - (ii) $f(I_1) \supset I_2$;
 - (iii) $f(I_2) \supset I_0$ [1 mark].
- Therefore, by the IVT, there are intervals $K_i \subset I_i$ such that
- (i) $f(K_0) = I_1$;
 - (ii) $f(K_1) = I_2$;
 - (iii) $f(K_2) = K_0$ [1 mark].
- Consequently, f^3 maps K_0 to itself [1 mark]. Therefore, f^3 has a fixed point in K_0 , call it z [1 mark]. If z does not have prime period 3 for f , then it must

be a fixed point of f [1 mark]. Then $z = f(z)$ so z must lie in both K_0 and K_1 , and $z = f^2(z)$ so z must lie in K_1 and K_2 , too. But $K_0 \subset I_0$ and $K_2 \subset I_2$ are disjoint [1 mark]. Absurd. Therefore, z has prime period 3. QED

- (c) (i) Solving $f_\mu(x) = x$, we get $x = \pm\sqrt{-\mu}$ [1 mark].
Thus, we have a f.p. iff $\mu \leq 0$ [1 mark].
(ii) At $\mu = 0$, the f.p.s collide and disappear. This is a saddle-node bifurcation [1 mark].
(iii) There is a flip bifurcation at the parameter μ_* and f.p. x_* if $f'_{\mu_*}(x_*) = -1$ and $f'_\mu(x_\mu)$ passes through -1 at the same time [2 marks]. In this case $f'_\mu(x) = 1+2x$ which is positive for the positive f.p. and is -1 for the negative f.p. when $x_* = -1$ or $\mu_* = -1$. It is clear that the derivative moves through -1 as μ decreases. Therefore, there is a flip bifurcation only at $\mu_* = -1$ and $x_* = -1$ [2 marks].
To determine super-/sup-criticality, we use the Schwartzian derivative:

$$D_s\{f\} = \frac{f'''}{f'} - \frac{3}{2} \left[\frac{f''}{f'} \right]^2. \quad [1 \text{ mark}]$$

As $f''_\mu = 0$, $f_\mu = 2$ and $f'_{\mu_*}(x_*) = -1$, we see that

$$D_s\{f_{\mu_*}\}(x_*) < 0.$$

Hence, the flip bifurcation is supercritical [1 mark].

- (iv) Bifurcation diagram [3 marks]

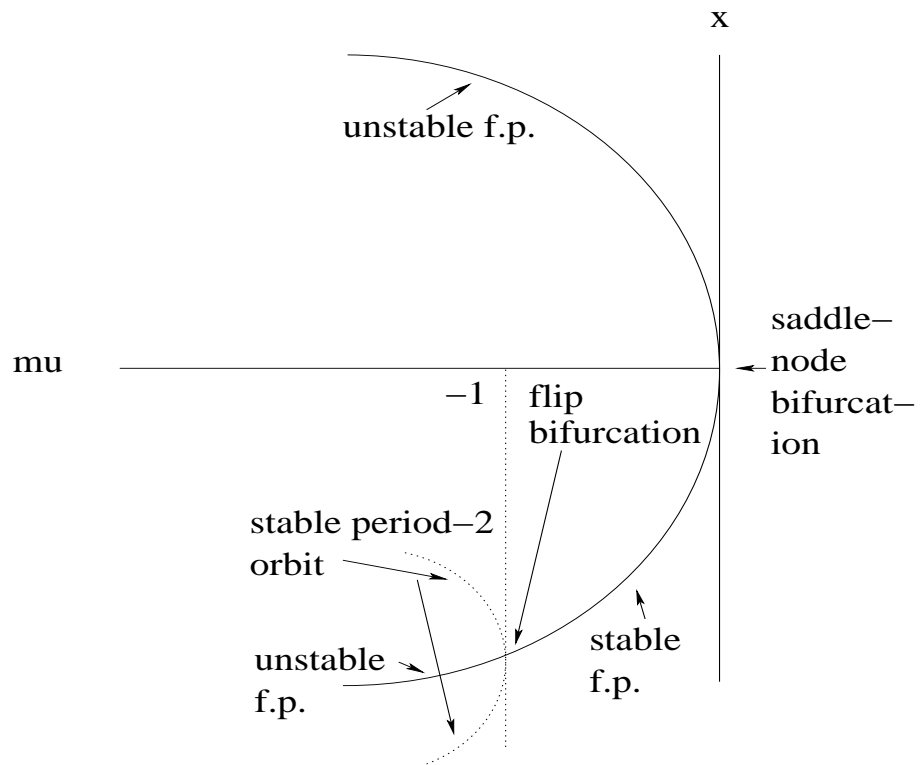


FIGURE 3. The bifurcation diagram for f_μ .