M4 Dynamical Systems

May 2005 — Questions

2 hours; best 3 answers count.

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Dynamical Systems

1. Consider the two-dimensional system

$$x_{n+1} = -x_n + 3y_n - \frac{15}{8} (x_n - y_n)^3,$$

$$y_{n+1} = -\frac{3}{2} x_n + \frac{7}{2} y_n - \frac{15}{8} (x_n - y_n)^3,$$

where $x_i, y_i \in \mathbb{R}$.

- (a) Show that there is a saddle-point at the origin.
- (b) Give the definitions of the stable and unstable subspaces of the origin and find their equations.
- (c) Introduce the vector $\begin{pmatrix} u_n^+ \\ u_n^- \end{pmatrix}$ which is defined via

$$\left(\begin{array}{c} x_n \\ y_n \end{array}\right) = \left(\begin{array}{cc} a & 1 \\ 1 & b \end{array}\right) \left(\begin{array}{c} u_n^+ \\ u_n^- \end{array}\right),$$

where $\begin{pmatrix} a \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ b \end{pmatrix}$ are vectors aligned with the stable and unstable subspaces, respectively. Thereby, show that the system may be expressed in the form

$$u_{n+1}^{+} = \alpha u_{n}^{+},$$

 $u_{n+1}^{-} = \beta u_{n}^{-} + \gamma (u_{n}^{+})^{3};$

and evaluate the constants a, b, α , β and γ .

- (d) State the stable manifold theorem and show that
 - i. the stable manifold is given exactly by

$$u^{-} = \delta (u^{+})^{3}$$
:

ii. the unstable manifold is given exactly by

$$u^+ = \rho$$
;

and evaluate the constants δ and $\rho.$

(e) Sketch the stable and unstable manifolds in the (u⁺, u⁻) plane. Include in your sketch a few representative orbits and indentify the stable and unstable subspaces.

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2. Consider the map

$$x_{n+2} = x_{n+1} - x_n + 2(2x_n - x_{n+1})^3, (*)$$

where $x_i \in \mathbb{R}$.

- (a) Find the fixed points of this map.
- (b) Use the corresponding linearized map to discuss the stability of the fixed points.
- (c) Let $z_n = x_n + \varepsilon x_{n+1}$ where $\varepsilon \in \mathbb{C}$. Show that, by choosing ε appropriately, the system (*) may expressed as

$$z_{n+1} = \alpha z_n + \beta_1 (z_n)^3 + \beta_2 (z_n)^2 \overline{z}_n + \beta_3 z_n (\overline{z}_n)^2 + \beta_4 (\overline{z}_n)^3$$

and calculate the complex-valued constants α , β_1 , β_2 , β_3 and β_4 .

(d) Explain briefly (without performing any calculations) how the system may rewritten in terms of a new variable ζ_n as

$$\zeta_{n+1} = \alpha \zeta_n + b \zeta_n^2 \overline{\zeta}_n + O(|\zeta_n|^4)$$

and express b in terms of ε .

(e) Using (d), show how the stability of the origin depends on b/ε and thereby comment upon the stability of the origin for the system (*).

3. Consider the map

$$H_{\mu}(x) = \mu \tan^{-1} x \,,$$

where x is a real-valued variable and μ is a real-valued parameter.

- (a) How many fixed points are there? Specify the ranges of values of μ for which they exist.
- (b) Calculate the Schwarzian derivative of H_{μ} .
- (c) Describe the bifurcations which occur for

i.
$$\mu = 1$$
,

ii.
$$\mu = -1$$
.

If there are flip bifurcations, state whether they are supercritical or subcritical. You may wish to make use of the following Taylor series expansion:

$$\tan^{-1} x = x - \frac{x^3}{3} + \frac{x^5}{5} - \dots,$$

for |x| < 1.

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(d) Sketch the bifurcation diagram in the (μ, x) plane; indicate the stability of the fixed points in your diagram.

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- 4. (a) Suppose a continuous mapping G has a period-3 orbit (a, b, c) where a < b < c.
 - i. Show that G has orbits of period 1 and period 2.
 - ii. Show that G has orbits of prime period n for all n > 3.
 - (b) Consider the \mathbb{R}^2 map represented as

$$\mathbf{x}_{n+1} = \mathbf{F}(\mathbf{x}_n) \tag{\dagger}$$

where

$$\mathbf{x}_{n+1} = \begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix}, \quad \mathbf{x}_n = \begin{pmatrix} x_n \\ y_n \end{pmatrix}, \quad \mathbf{F}(\mathbf{x}_n) = \begin{pmatrix} y_n + \nu \\ y_n^2 - x_n^2 \end{pmatrix},$$

and ν is a real-valued parameter.

- i. Find the $\begin{pmatrix} x \\ y \end{pmatrix}$ fixed points of the map (†) in terms of ν .
- ii. If the map (†) undergoes a Hopf bifurcation, what can you infer about the eigenvalues of the Jacobian matrix of derivatives of **F**?
- iii. Find the value of ν , and the corresponding $\begin{pmatrix} x \\ y \end{pmatrix}$ point, at which the map
 - (†) undergoes a Hopf bifurcation.